



Design, Integration and Testing Small Satellites

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Outline

- ❑ Small Satellite Classification
- ❑ AraMiS architecture:
- ❑ Concept of Tiles and Modules
- ❑ Smart Harness:
 - ❑ Module Life cycle
 - ❑ Spacecraft configurations
- ❑ Conclusion

Typical Classification of Small Satellites

	Mass (kg)	Altitude (km) Orb period	Project lifetime	Total Cost (M\$)	Cost/Mass¹ (k\$/kg)
Mini	100 - 500	1000 – 5000 (2 – 3 hrs)	4 - 7 yrs	10-150	200
Micro	10 – 100	500 – 2000 (1.6 - 2 hrs)	2 - 5 yrs	1-30	400
Nano	1 - 10	300 – 800 (1.4 – 1.7 hrs)	2 - 3 yrs	0.1-10	800
Pico	0.1 – 1	200 - 400 (1.4 – 1.5 hrs)	1 - 2 yrs	0.05-2	1600
Femto	< 100 g	200 – 400 (1.4 – 1.5 hrs)	1 yrs	< 0.05	3200

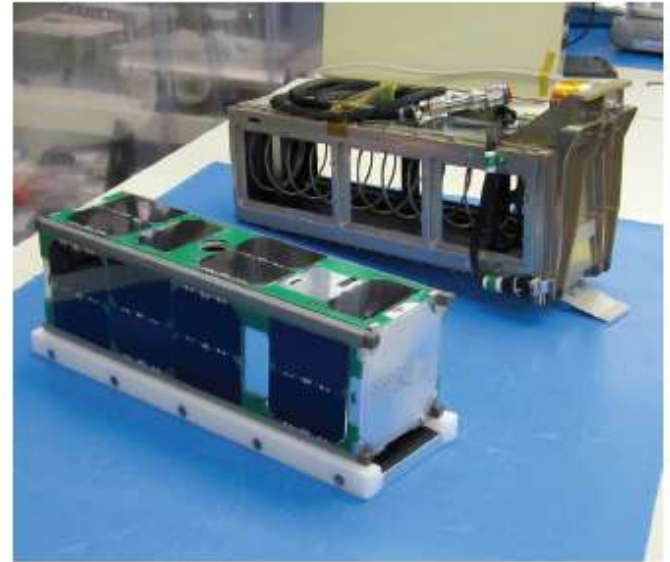
1 – Indicative values

CubeSat Standard

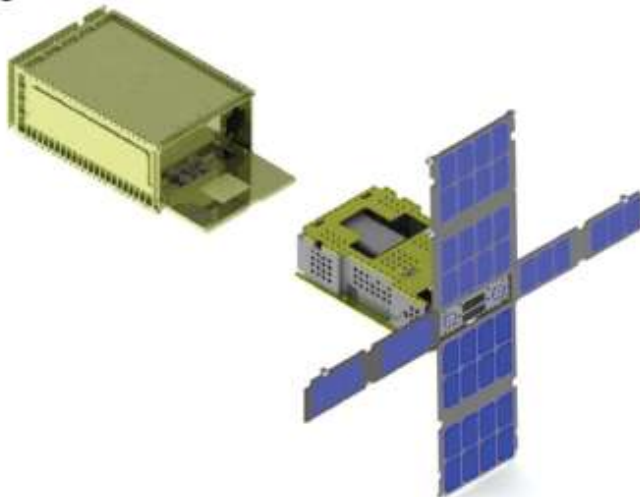
A



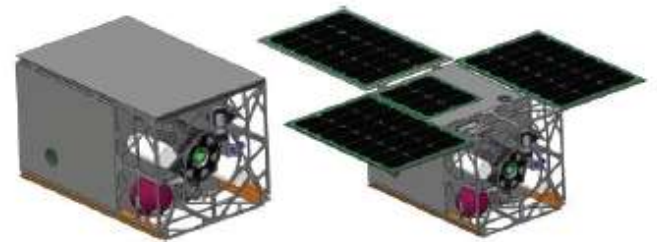
B



C



D

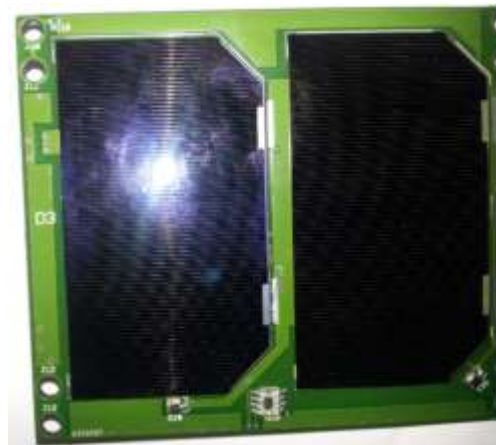


ARAMIS Approach

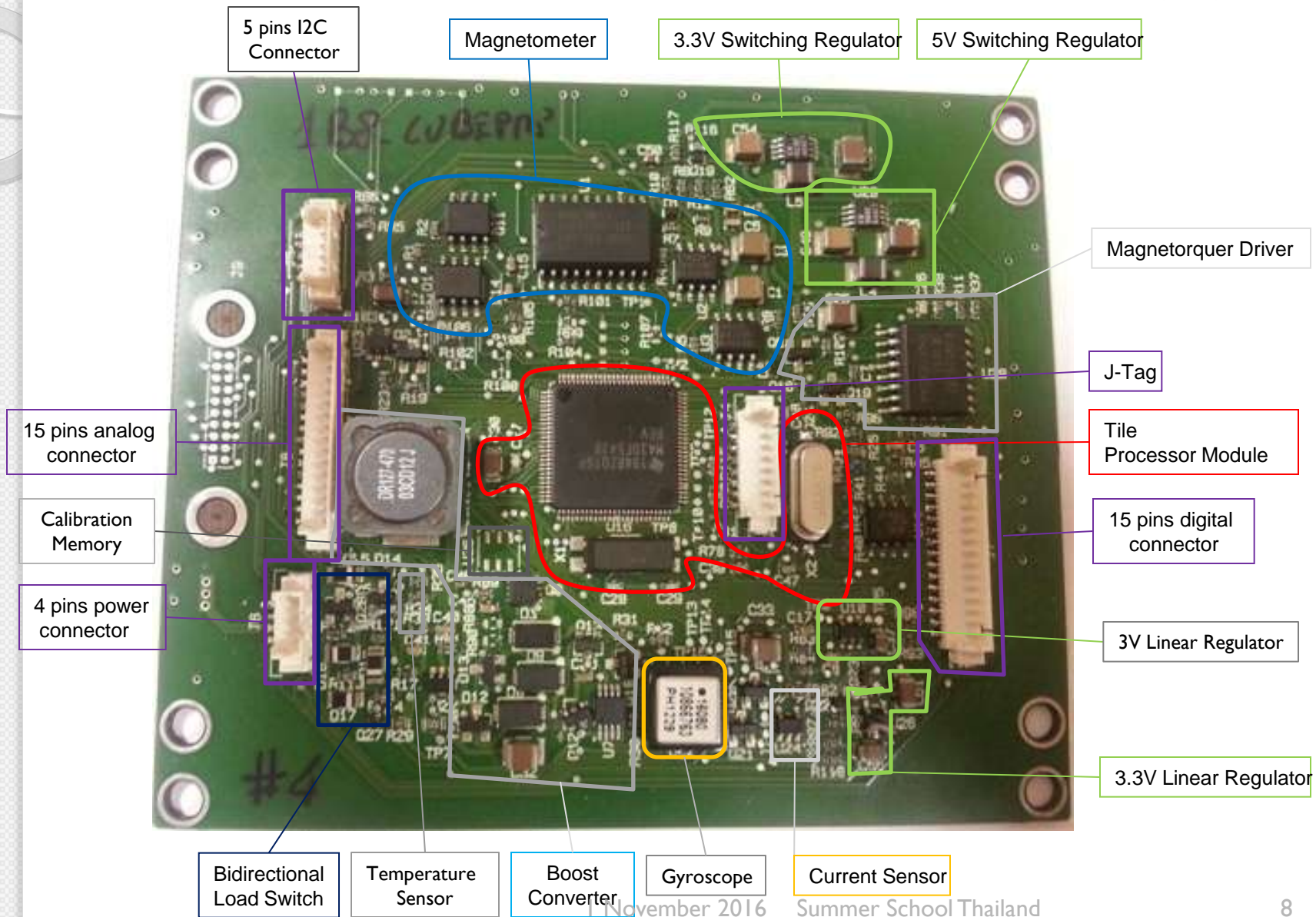
- ❑ **ARAMIS** (Modular Architecture for Satellites) is an innovative modular architecture for flexible and more demanding satellite configurations.
- ❑ **Panel bodies or tiles**
 - ❑ Different size and technology
 - ❑ Power and data standardized interfaces
- ❑ **Modularity**
 - ❑ Mechanical, electronic and testing level
- ❑ **Low cost**
 - ❑ Design, qualification and test cost shared among multiple modules
- ❑ The size of the satellite varies based on payload demands

Hardware Architecture of Tile (2)

- ❑ CubeSat standard: (8.25 x 9.8cm²) tile, with all electronic components integrated and compatible with CubeSat dimensions.
- ❑ All structure on PCB only
- ❑ All the subsystems integrated on each tile

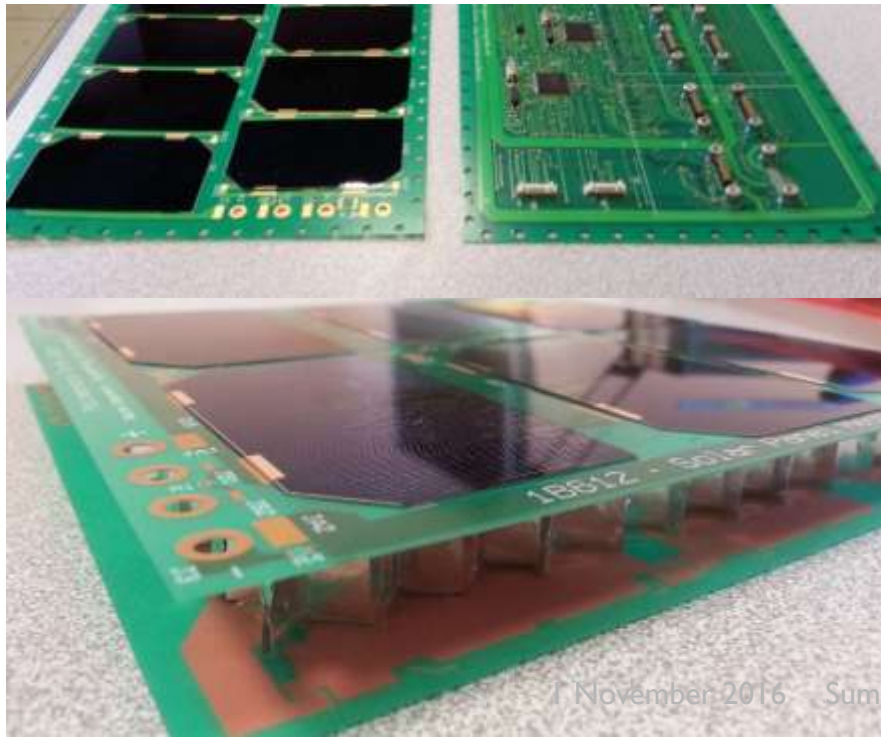


Hardware Architecture of Tile (2)



Hardware Architecture of Tile (3)

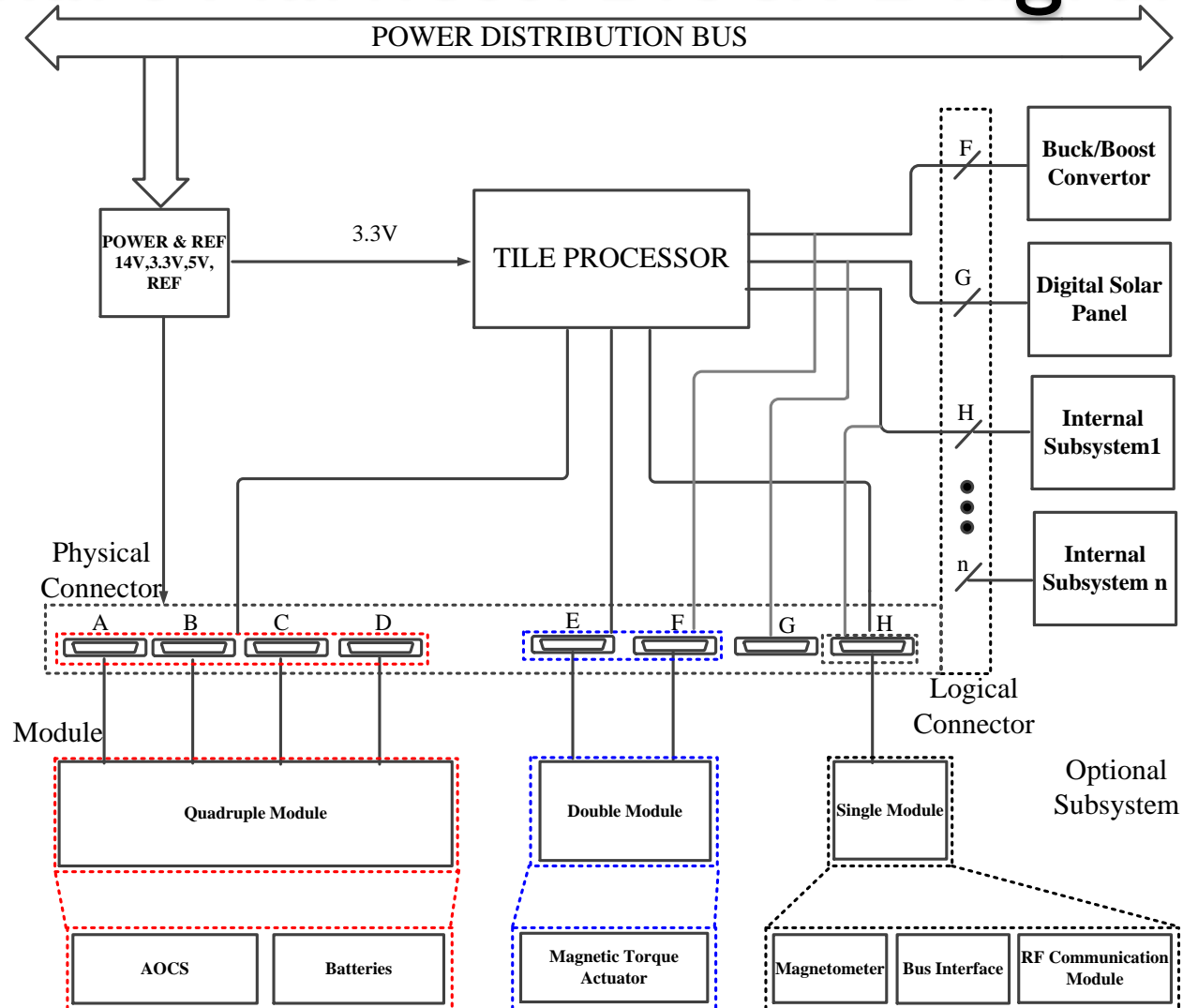
- Honeycomb Structure: 16.5x33 cm² tile, with 10mm thick honeycomb structure for more rigid and larger structures for more rigid and larger structures



MOCKUP

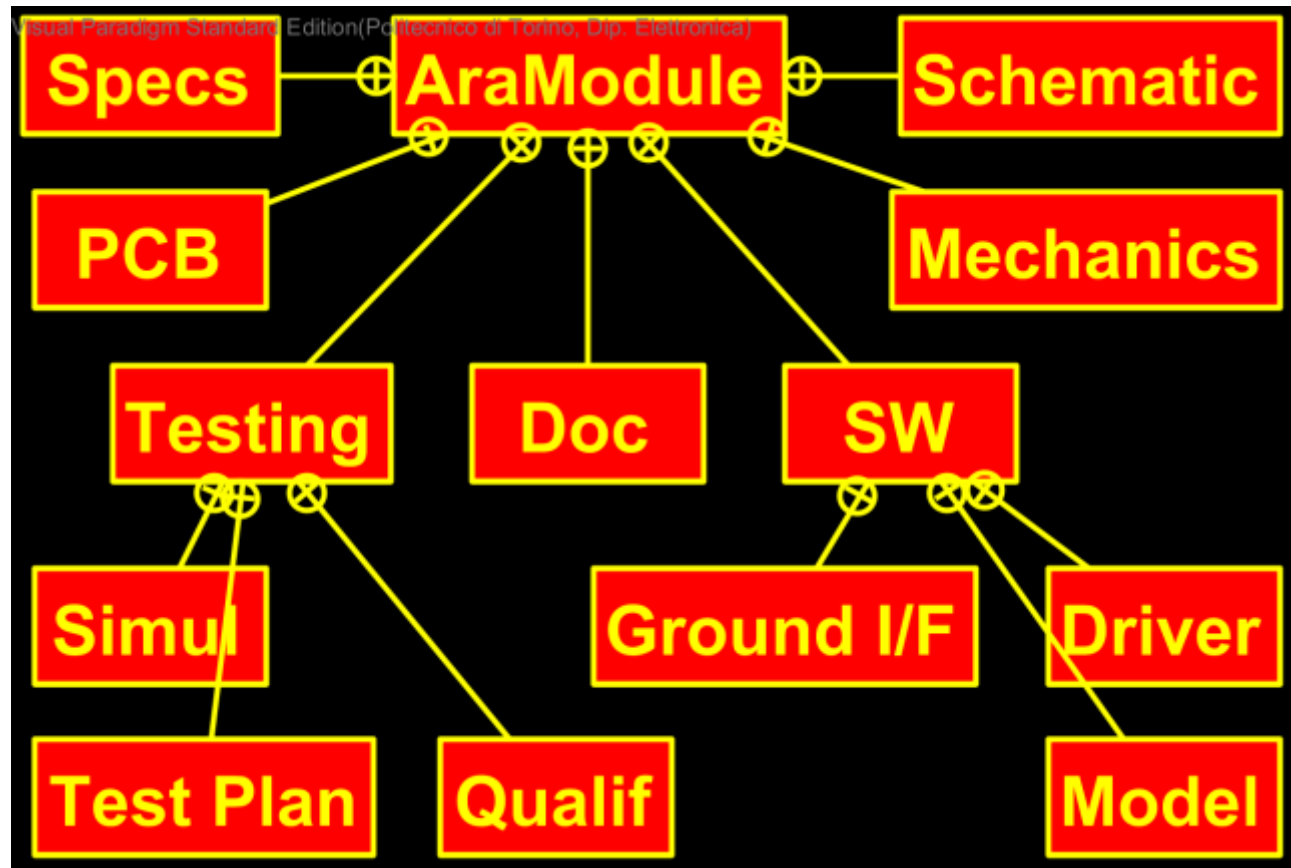


Smart Harness: Block Diagram



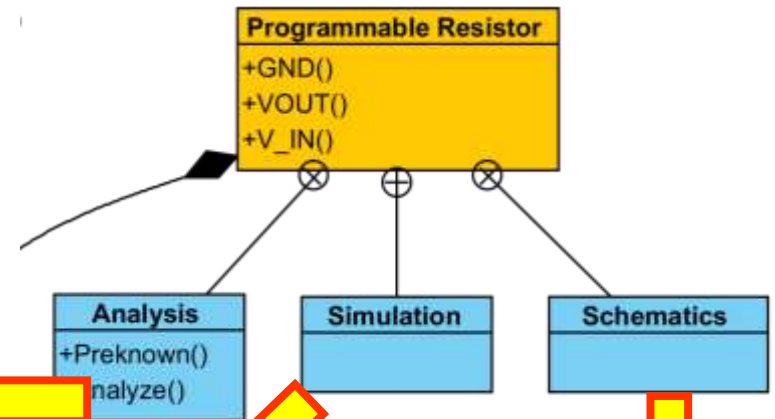
AraMiS → “AraModules” and “Tiles”

An AraModule is a small P&P subsystem

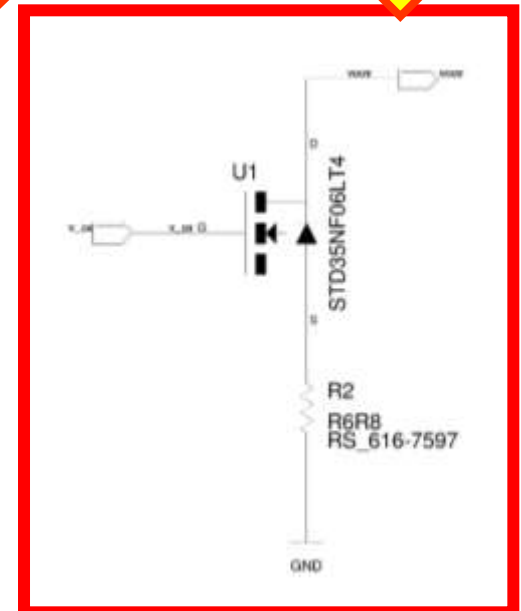
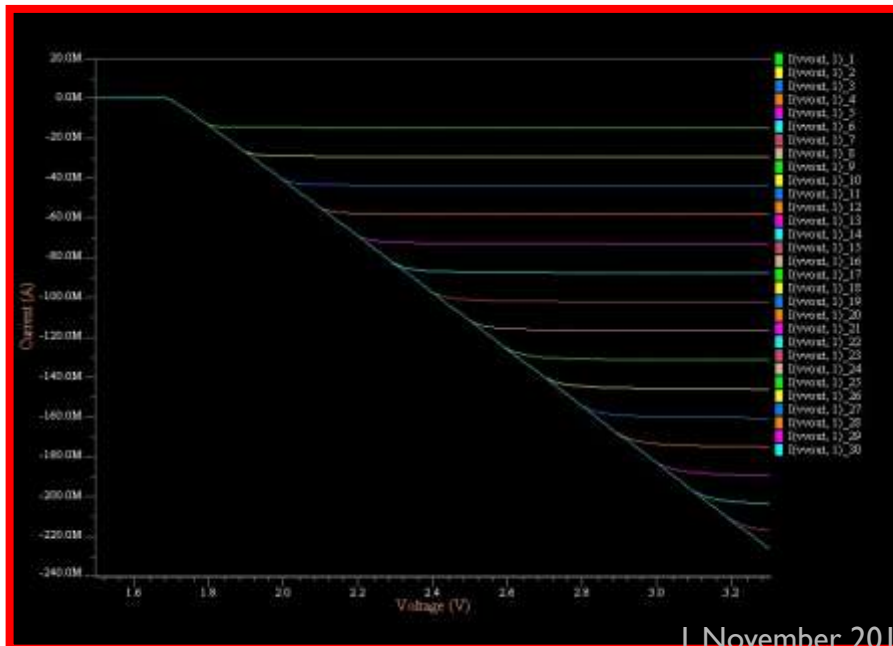


AraMiS → “AraModules” and “Tiles”

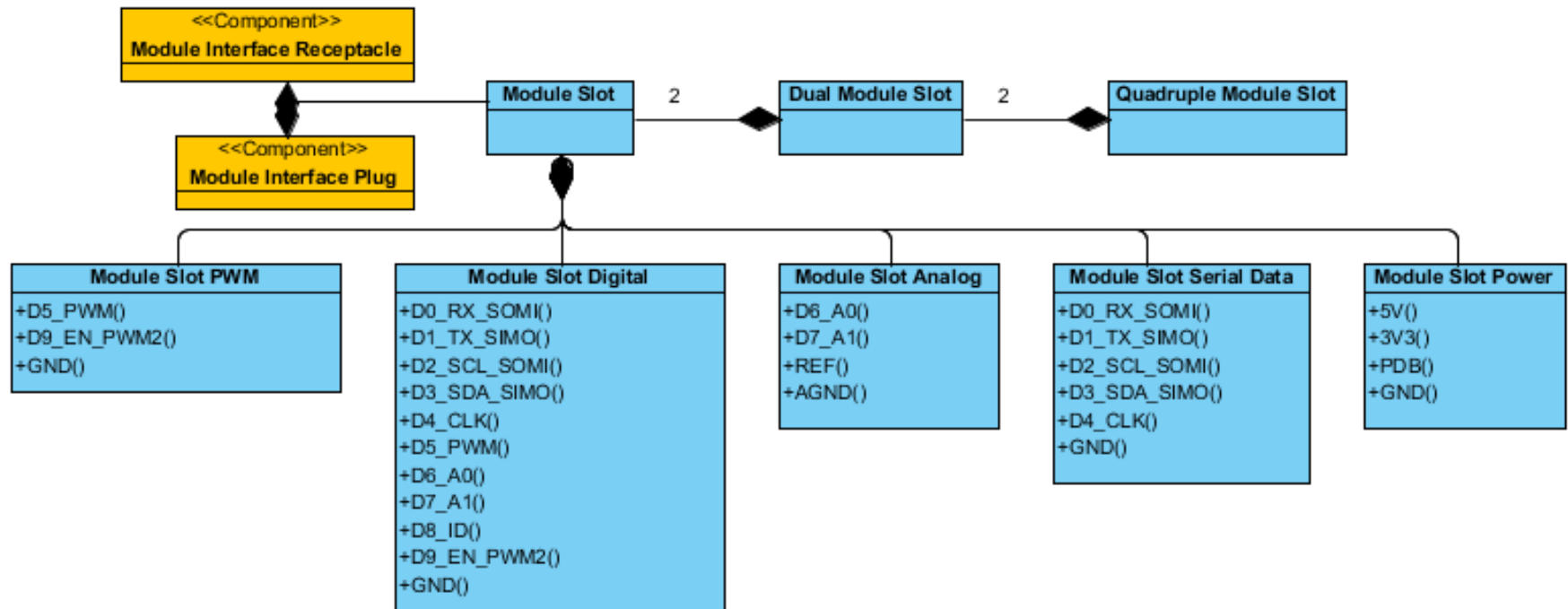
Inside an AraModule.



$$I = \frac{(1 - 2.k.R_s.V_T) + 2.k.R_s.V_{in} - \sqrt{4.k.R_s.(V_{in} - V_T)}}{2.k.R_s^2}$$



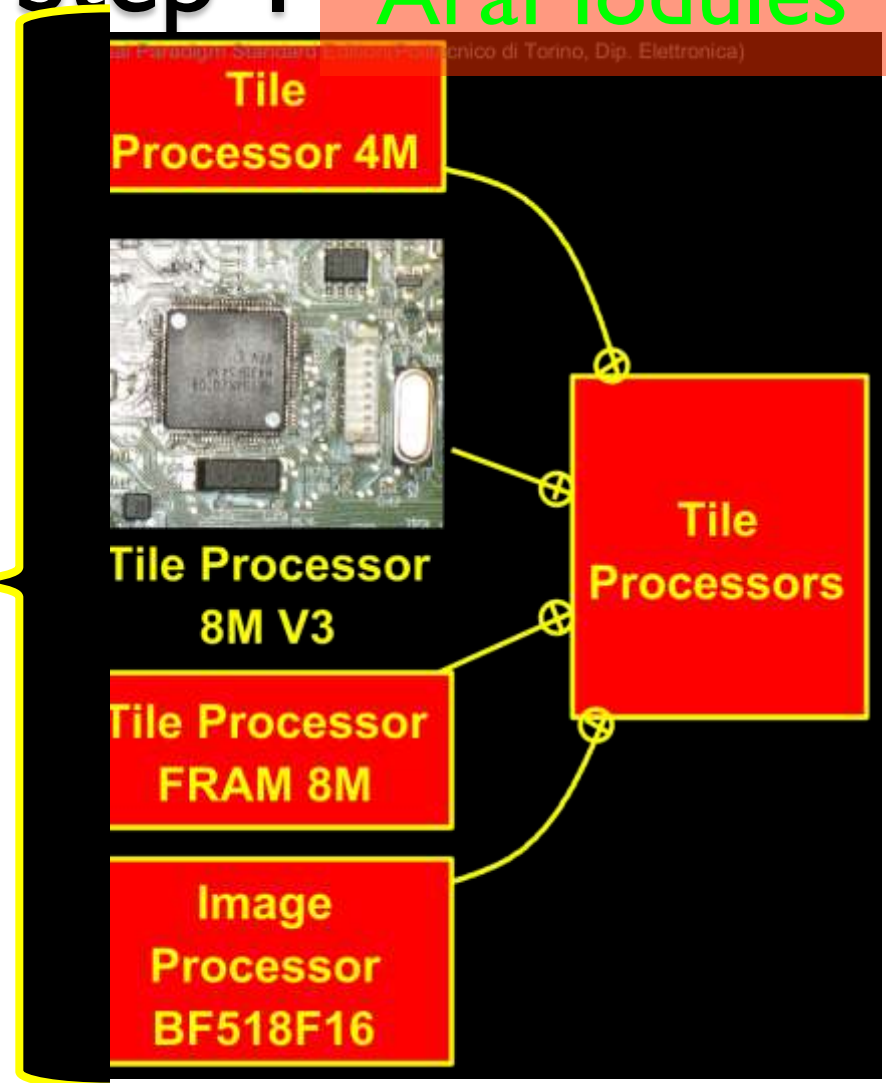
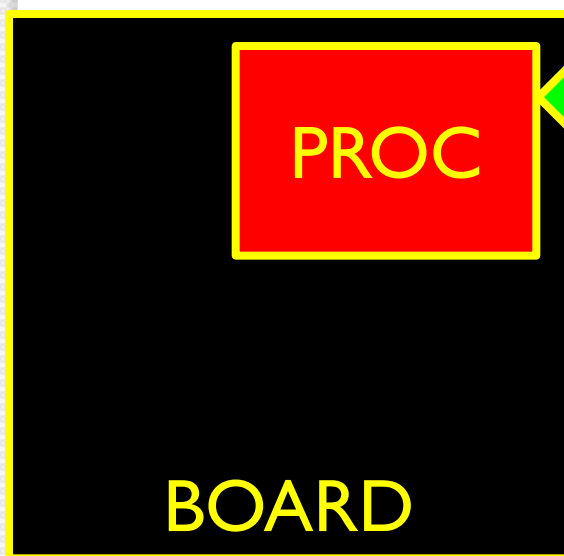
AraModule: Electrical Interface



AraMiS P&P – Step 1

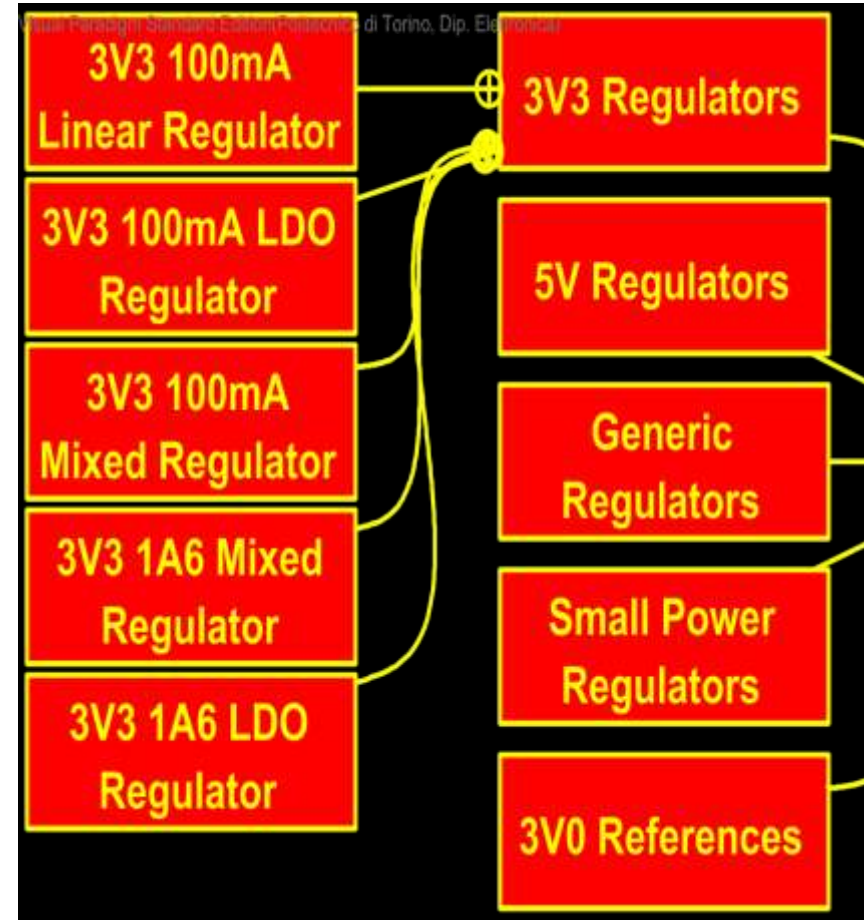
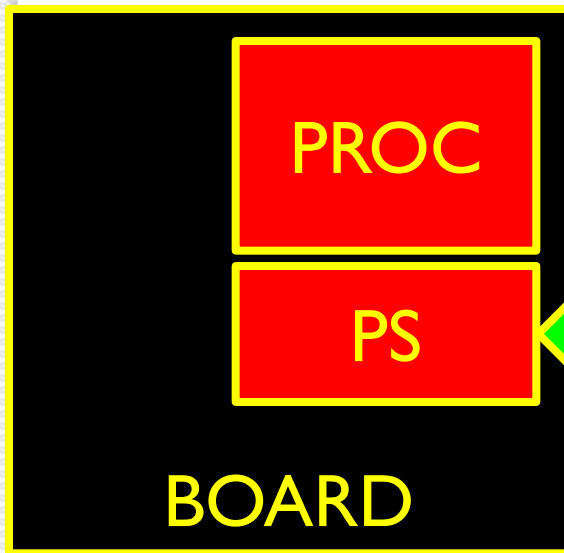
AraModules

- select processor from a library
- add to “virtual board”



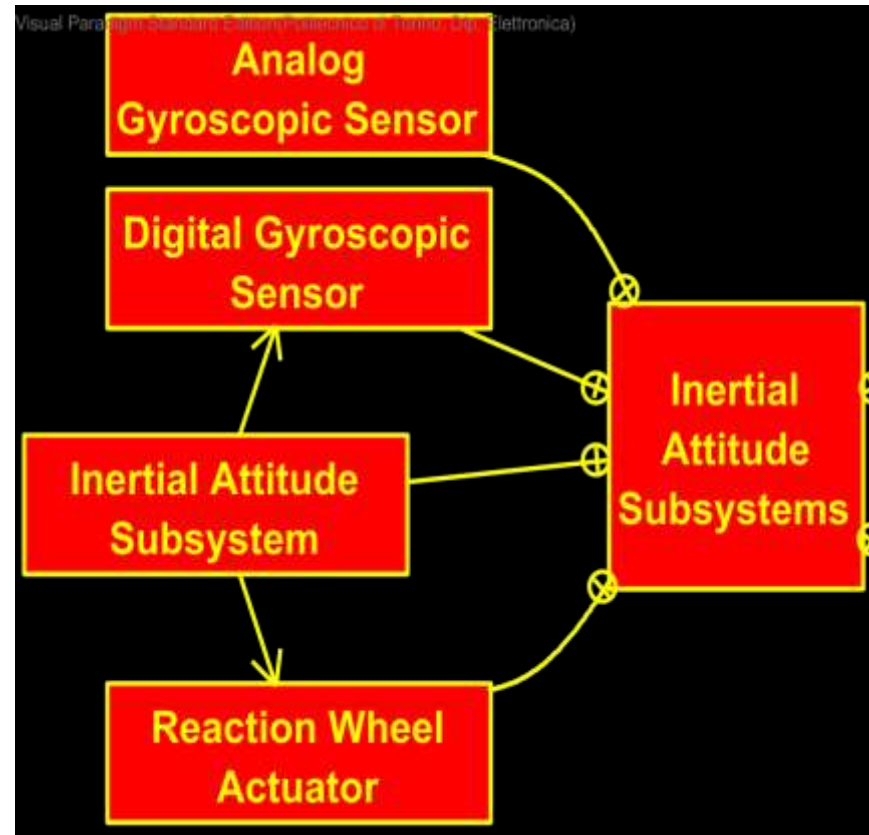
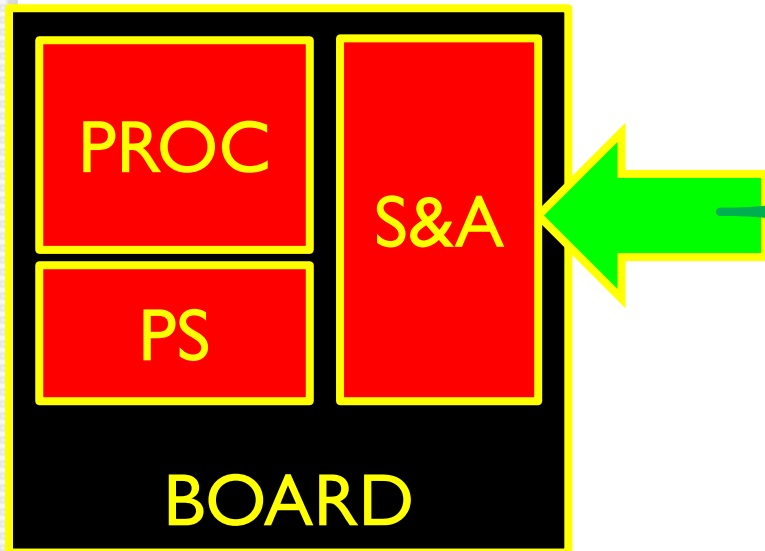
AraMiS P&P – Step 2

- a) select power supply from a library
- b) add to “virtual board”



AraMiS P&P – Step 3

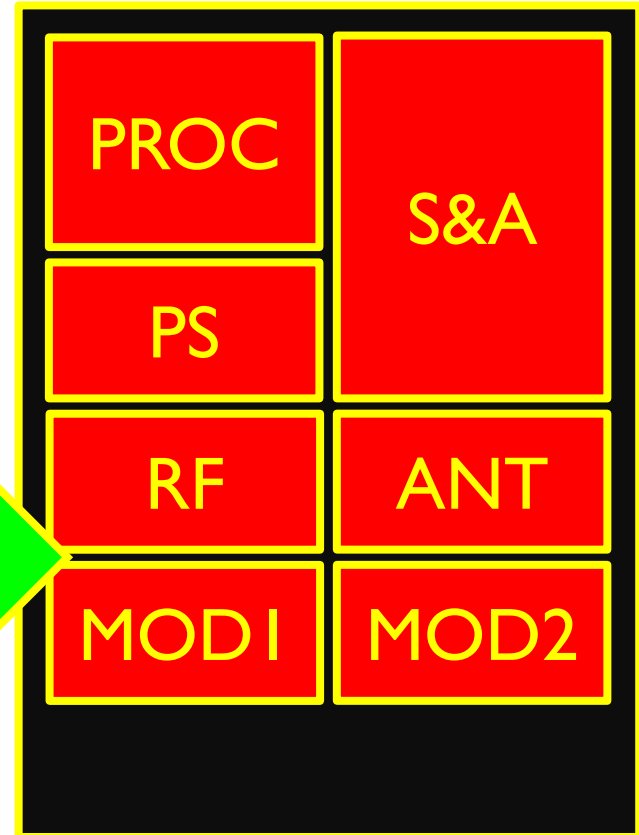
- a) select AOCS sensors and actuators...
- b) add to “virtual board”



AraMiS P&P – Step 4

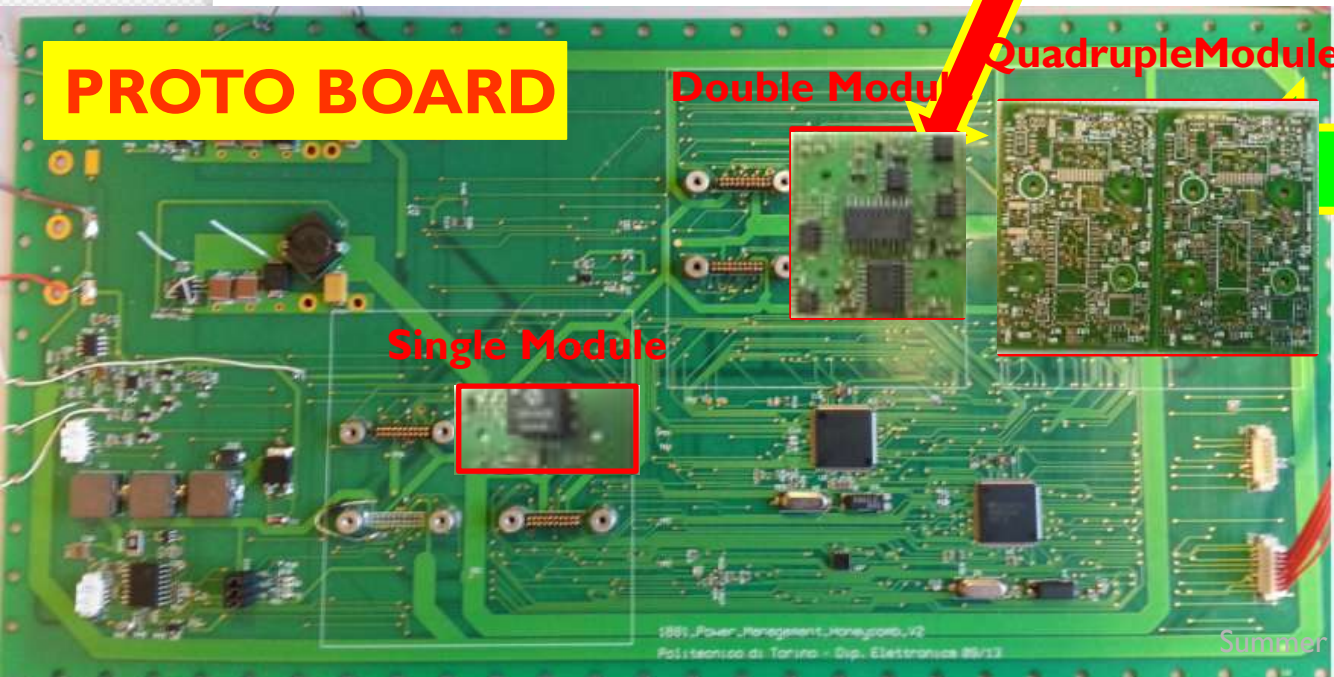
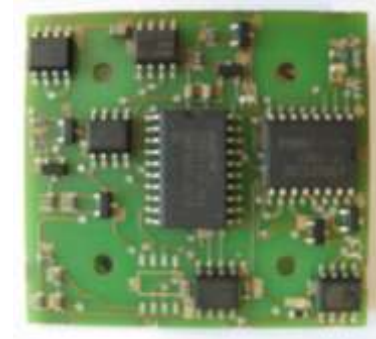
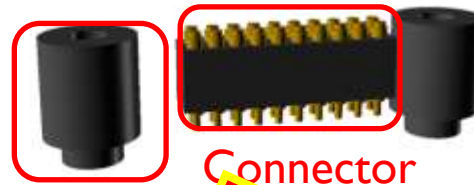
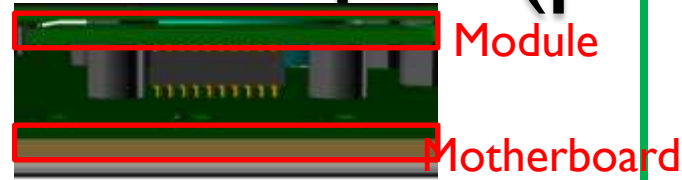
select and add:

- a) RF module(s)
- b) antenna(s)
- c) Other sensors
- d) On-board modules
- e) Payload support
- f) Any other...



AraMiS P&P – Step 5 (proto)

- a) take corresponding proto modules
- b) assemble to proto system

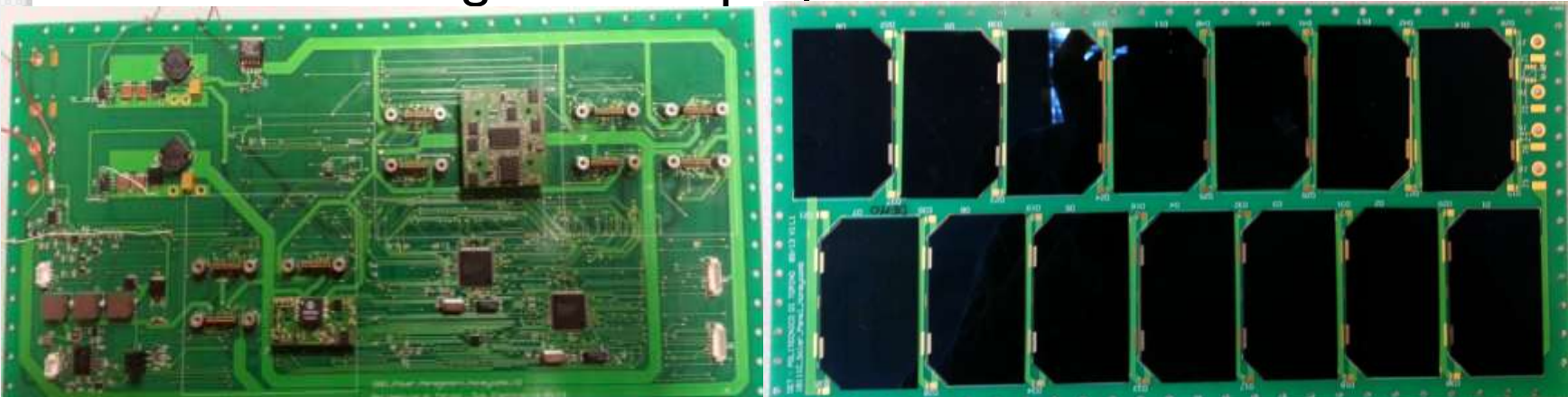


Smart Harness: Spacecraft Configurations

- ❑ Design the new subsystems either on single, double or quadruple module configuration.
- ❑ Test the subsystems on ground using development board.
- ❑ Integrate each physical module in a **physical module based satellite configuration**.
- ❑ Embed the logical modules in the main tile for a **Satellite on demand configuration**.
- ❑ The Satellite on demand configuration can be altered very easily for **Reusable design configuration**

Physical Module Based Configuration

- ❑ Develop standard tiles hosting multiple connectors
- ❑ Physical daughter boards connected to the tile via pluggable connectors
- ❑ The subsystem module only plugged if mission needs it.
- ❑ High level of design flexibility, testability and upgradability
- ❑ Testing of modules, tiles and whole satellite is needed
- ❑ For teaching/research purposes



Satellite on demand Configuration

- ❑ Already tested modules integrated inside the PCB.
- ❑ **Reusability** of physical subsystem modules
- ❑ Permanent configuration
- ❑ Testing of modules: not required
- ❑ Testing of tiles and mission is required only
- ❑ CubeSat standard tile built using this approach



Reusable design configuration

- ❑ Optimised spacecraft configuration based on mission requirements
- ❑ **Reuse of** the **satellite on demand** configuration
- ❑ Minor addition or removal of subsystems on customer demands
- ❑ Follows the **Cheaper-Faster-Better** philosophy
- ❑ Module and tile testing: not required
- ❑ Only mission testing is needed for this configuration

Conclusion

- ❑ The design technique achieves simple-faster-better design philosophy
- ❑ The modularity, flexibility and testability has been achieved at mechanical, electrical, protocol and testing level.
- ❑ Multiple spacecraft configurations possible with very short development times.

Thank You !!!